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## LANDMARK

# ORBITAL NAVIGATION PLAN FOR APOLLO 7

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MISSION PLANNING AND ANALYSIS DIVISION

MANNED SPACECRAFT CENTER  
HOUSTON, TEXAS



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NAVIGATION PLAN FOR APOLLO 7 (NASA)  
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PROJECT APOLLO

LANDMARK ORBITAL NAVIGATION PLAN FOR  
APOLLO 7

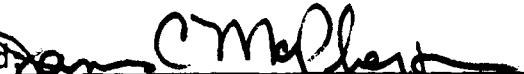
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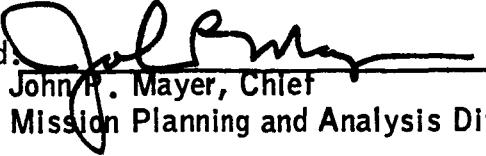
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MISSION PLANNING AND ANALYSIS DIVISION  
NATIONAL AERONAUTICS AND SPACE ADMINISTRATION  
MANNED SPACECRAFT CENTER  
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## LANDMARK ORBITAL NAVIGATION PLAN FOR APOLLO 7

By Richard E. Eckelkamp

### SUMMARY

This report presents the nominal navigation plan for orbital navigation for Apollo 7. Included are the landmark sighting schedule, the times for vector and schedule uplinks, and the erasable weighting structure load.

### INTRODUCTION

One of the test objectives of the Apollo 7 mission (Mission C, or AS-205/CSM-101) is to exercise the procedures and programs of a new space-navigational method, landmark sighting, and to evaluate its potential. This method is capable of determining both the coordinates of the landing site and the orbit of the CSM during the lunar missions.

Basically, telescope or sextant sightings on landmarks are processed through a statistical filter in order to correct the command module computer's (CMC's) state vector for the command and service modules (CSM) or a landmark, or both. As currently planned, during the first lunar landing mission this orbital navigation method will be used for landing site determination in the landmark or landing site mode, i.e., the updating matrix will be a  $3 \times 3$  and will update the coordinates of the landmarks only. This procedure determines the landing site position relative to the CSM-LM orbit and/or transmits the mark data by telemetry to the ground processor without affecting the vehicle position and velocity portion of the state vector. Two days of orbital navigation are planned for Apollo 7. On day 3, the  $3 \times 3$  mode will be exercised; on day 6, the  $9 \times 9$  mode. This order is preferred because

1. The astronaut will be aided by the auto-optics being more accurate for  $3 \times 3$  navigation since updates are provided by MSFN.
2. More unknown landmarks must be used at the beginning of sighting passes on day 3, a condition which is detrimental to  $9 \times 9$  navigation and indifferent for  $3 \times 3$ .

3.  $3 \times 3$  is the planned method for lunar mission use and should be given preference in the sequencing of tests in the event that fuel constraints or the premature termination of the mission prevent the day 6 exercise.

#### SELECTION OF A NAVIGATION PLAN

Since the primary purpose of landmark sightings during Apollo 7 is to provide data for postflight evaluation of the method as a navigational tool, it is necessary that the onboard state vector and other pertinent data be downlinked. This requirement plus the requirement for accurate RTCC state vectors for postflight analysis indicate the need for maximum MSFN coverage. Without this coverage no comparison would exist for the command module computer (CMC) vectors. Secondly, use of the recorder presents data limitations due to the speed of readout over a station.

Accordingly, the majority of sightings must be made during the passes over the United States, Mexico, and Central America. Only those orbits during which the crew timeline and ground coverage were optimal were investigated. Maneuvers and some other test objectives also require optimal coverage. With these considerations orbital navigation will occur on days 3 and 6 (ref. 1). It should be noted that, if during real-time mission planning, orbital navigation should be moved to another day, its exercise still demands optimal MSFN passes for success.

#### Selection of a Sighting Schedule

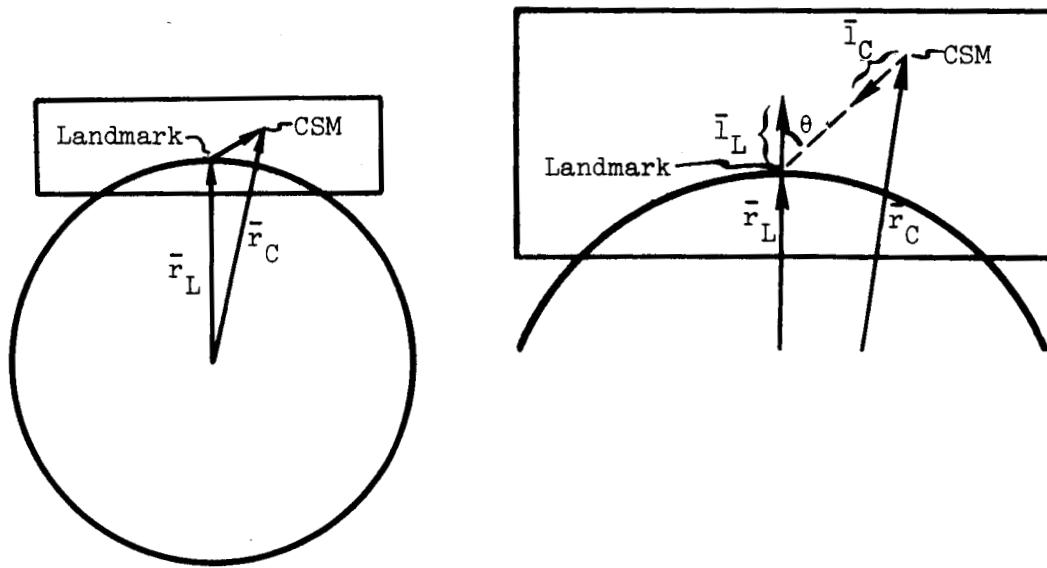
To determine the availability of landmarks during the optimal passes, an ephemeris of the CSM was first generated from the Apollo 7 operational trajectory (ref. 2). The initial vectors (in the nearest Besselian year coordinate system) for the ephemeris were

Day 6	Day 3
X, ft . . 21543591.	X, ft . . 21657322.
Y, ft . . -2615935.	Y, ft . . 2246621.
Z, ft . . 1001103.	Z, ft . . -1249560.
$\dot{X}$ , fps . . 1811.	$\dot{X}$ , fps . . -1598.
$\dot{Y}$ , fps . . 21716.	$\dot{Y}$ , fps . . 21602.

Day 6	Day 3
$\dot{z}$ , fps . . . . 13110.	$\dot{z}$ , fps . . . . 13246.
t . . . . . 8557.9481 min g.e.t.	t . . . . . 4374.0918 min g.e.t.

The vehicle area was taken to  $129.4 \text{ ft}^2$ , and the drag parameter,  $0.137798 \text{ ft}^2/\text{slug}$ . At designated times a check was made to see if any landmarks were visible. Constraints on the check are discussed in the following sections.

Occultation Constraint.- A necessary property of a usable landmark (see illustration below) is that it not be occulted by the horizon.



Let  $\bar{r}_L$  = the vector from the center of the earth to the top of the landmark.

$\bar{l}_L$  = a unit vector pointing along  $\bar{r}_L$

$\bar{r}_C$  = the vector from the center of the earth to the CSM

$\bar{l}_C$  = a unit vector pointing along  $(\bar{r}_L - \bar{r}_C)$

Now, using the definition of the dot product,

$$\cos \theta = -\bar{I}_C \cdot \bar{I}_L$$

$$\theta = \cos^{-1} [-\bar{I}_C \cdot \bar{I}_L]$$

From results of the Gemini program,  $\theta$  must be less than  $55^\circ$ , if a landmark is to be perceived. Some disagreement exists, however, on the value of  $\theta$ . Since its value is critical for fuel calculations during landing site observations in lunar orbit,  $\theta$  should be tested during an earth orbit mission.

Lighting Constraint.- Most critical among the constraints to be tested on Apollo 7 is lighting. The sun elevation angle at a given landmark directly affects whether it can be distinguished from the surrounding features. Despite the presence of an atmosphere on earth, much meaningful information can be derived from Apollo 7 which will be useful for lunar sighting. Albedo effects on the moon are secondary to those of sun elevation angle. The value for the minimum elevation angle affects the sequencing of landmark and landing-site sightings and possibly introduces constraints on the lunar launch window.

Weather Constraint.- Cloud coverage will probably occult many otherwise acceptable landmarks. During real time, information on cloud coverage will be available through the MSC Weather Bureau and will be based on local forecast and weather reports, satellite data, and airplane pilot reports. For selection of the premission nominal plan, results of cloud coverage probability studies were used when available. Alternate landmarks were provided when available for areas with highly probable cloud coverage.

The Sighting Schedule.- Table I indicates the view periods for the available landmarks. Landmark numbers (ref. 3) are in the left-hand column. Time of acquisition, accurate to the nearest 7.5 seconds is given in the second column. At succeeding increments of 7.5 seconds, the landmarks were checked again. If visible, a number representing  $\theta$  in the previous discussion appears. A pass is measured from  $90^\circ E$  longitude eastward.

Table II presents the nominal Apollo 7 sighting schedule. Alternate landmarks in the general area of the primary ones are given in the right-hand column. The landmarks selected were chosen because they could be easily distinguished (ref. 4). Those which might be difficult to recognize were rejected or chosen as alternates and indicated with a footnote. Unknown landmarks were selected at convenient times when

the CSM groundtrack was void of known landmarks and was over land.

#### Update and Alignment Times

The times for ground uplink for the state vector and landmark schedule (which will be discussed below) are contained in table III. Realignment of the IMU must occur prior to each sighting pass. This procedure prevents the insertion of large IMU errors into the observation data, an occurrence which would seriously affect the usefulness of the data for postflight evaluation. For both days, the state vector need be uplinked only before the first pass. The vector uplink should be voice checked through use of CMC program P21 or DSKY display of the erasable cells containing the vector. The latter procedure allows the astronaut to record the vector for possible use if a MSFN vector is needed for some contingency. For  $3 \times 3$  navigation, it is desirable, but not mandatory to uplink the state vector before the second and third passes if the uplink does not interfere with the IMU realignment. If the uplink interferes, it should be omitted.

#### Weighting Structure Load

Table IV contains the values for the initial W matrix to be used for  $3 \times 3$  and  $9 \times 9$  navigation. The values for  $3 \times 3$  will be loaded premission. Sometime after the  $3 \times 3$  tracking and before the  $9 \times 9$  tracking, the values for  $9 \times 9$  must be punched into the erasable memory by the astronaut and verified by the flight controller. (A document describing the selection of the weighting structure load will be published.)

#### Operational Constraints

When processing landmark data (after taking marks) while over an area without continuous MSFN coverage, the recorder must be turned on. Since the low-bit mode is advantageous for fast readout, it should be used. One disadvantage of the low-bit mode, however, is that the downlink list is scanned only every 10 seconds. Therefore, when utilizing the recorder while processing marks, it is essential to allow the delta r - delta v display to remain on the DSKY for at least a fraction over 10 seconds. This is the only way that the data for the particular mark can be recorded for future studies. For high-bit rate or for processing over tracking stations, the delta r - delta v display must remain on the DSKY for a fraction over 2 seconds.

To aid in acquisition of landmarks, the use of auto-optics positioning is available. Updating of the CSM vector each pass during  $3 \times 3$  navigation will aid auto-optics accuracy. During  $9 \times 9$  navigation auto-optics for the first landmark on the second pass may be inaccurate due to poor propagation. Later in the mission, e.g., on day 8, 9, or 10, some time should be devoted to the use of auto-optics with various perturbations on the state vector.

#### Data Requirements

Each landmark is to be marked five times as the CSM passes over it. A minimum of four distinct landmarks with five marks apiece are required for postflight analysis. If the scheduled known landmarks are not visible due to cloud coverage or inability to acquire, other known landmarks should be used. (Program P21 provides the CSM groundtrack). If no known landmarks are available, unknowns should be marked. Practice sessions before the actual planned three consecutive passes should be taken.

#### CONCLUDING REMARKS

The sighting schedule presented above was labeled the nominal Apollo 7 sighting schedule. During the mission any changes from the groundtrack presented in the operational trajectory affect which landmarks may be visible to the astronaut. For example, with a  $\theta$  of  $55^\circ$  (discussed above) he may see only  $2\frac{1}{2}^\circ$  to  $3^\circ$  on either side of his groundtrack, depending on his altitude. Secondly, a number of possible landmarks will be covered by clouds. Thirdly, the schedule needs to be planned so that visibility constraints are tested. (The latter can possibly be done in practice sessions.) For these reasons, the actual landmark tracking schedule will be uplinked real-time to the astronaut.

TABLE I.- AVAILABLE LANDMARKS

Landmark no	Time of acquisition, t, min g.e.t.	at t plus 7.5 sec	at t plus 15 sec	at t plus 22.5 sec	θ, deg	at t plus 30 sec	at t plus 37.5 sec	at t plus 45 sec	at t plus 52.5 sec
4	4383.87	54	54	51	54	52	54	42	45
6	4393.50	54	52	51	47	44	42	18	48
8	4393.50	50	55	51	47	39	31	14	27
10	4393.75	55	52	47	44	51	21		
18	4394.75	55	52	47	44	53	31		
20	4395.12	53	47	44	46	40	34		
37	4396.12	36	44	53	46	48	53		
44	4398.12	54	53	46	48	49	42		
45	4399.87	51	46	48	48	49	42		
43	4400.87	48	48	48	48	49	42		
46	4400.62	55	49	49	49	42	33		
47	4400.75	50	43	43	43	46	24		
44	4400.87	55	50	46	46	42	14		
45	4401.00	53	49	44	44	41	12		
46	4401.37	53	52	52	52	50	41		
47	4401.62	34	43	43	48	54	40		
44	4401.75	41	41	41	41	48	52		
45	4401.87	52	52	52	52	50	42		
43	4402.00	54	51	46	40	35	30		
46	4427.00	51	40	45	50	55	28		
224	4428.00								

(a) Day 3

## First sighting pass

Landmark no	Time of acquisition, t, min g.e.t.	at t plus 7.5 sec	at t plus 15 sec	at t plus 22.5 sec	θ, deg	at t plus 30 sec	at t plus 37.5 sec	at t plus 45 sec	at t plus 52.5 sec
5	4487.00	55	51	47	43	41	42	44	48
6	4488.00	52	47	40	33	27	25	29	36
7	4487.25	52	49	55	41	33	26	23	27
18	4488.25	43	49	55	47	33	26	30	34
	4488.37	55	54	55					
	4489.62	53	47						

## Second sighting pass

TABLE I.- AVAILABLE LANDMARKS - Continued

Landmark no	Time of acquisition, t, min g.e.t.	Second sighting pass - Continued						θ, deg	at t plus 22.5 sec	at t plus 15 sec	at t plus 7.5 sec	at t plus 0 sec	at t plus 30 sec	at t plus 37.5 sec	at t plus 45 sec	at t plus 52.5 sec
		41	48	54	47	45	44									
21	4490.62	41	48	54	47	45	44	46	49	49	49	49	49	49	49	52
20	4492.00	54	50	53	47	39	29	17	12	25	25	25	25	25	25	25
38	4492.25	53	44	44	40	51	43	43	45	48	48	48	48	48	48	52
39	4493.25	35	49	45	45	43	43	43	45	49	49	49	49	49	49	53
40	4495.25	53	49	48	45	45	43	35	27	23	23	23	23	23	23	32
48	4495.50	55	49	49	43	43	35	27	22	22	22	22	22	22	22	31
49	4495.75	55	49	50	48	48	48	50	52	52	52	52	52	52	52	52
49	4496.25	52	50	50	46	52	33	30	30	35	35	35	35	35	35	41
40	4496.50	39	46	46	45	39	33	30	30	35	35	35	35	35	35	35
52	4496.50	51	45	45	46	52	44	44	46	49	49	49	49	49	49	53
48	4496.75	39	46	46	46	46	44	39	35	35	38	38	38	38	38	43
50	4496.75	53	49	49	46	46	44	37	32	29	32	32	32	32	32	37
51	4496.75	54	49	49	44	44	43	35	24	11	3	17	17	17	17	29
53	4497.00	55	49	49	44	44	41	32	21	12	12	15	15	15	15	25
54	4497.25	51	44	44	48	48	41	32	21	12	12	15	15	15	15	25
55	4497.37	54	48	53	47	39	29	29	18	8	14	14	14	14	14	26
52	4497.50	48	53	53	47	39	33	29	30	35	35	35	35	35	35	41
56	4497.62	53	48	53	46	39	33	29	22	10	9	9	9	9	9	21
51	4497.75	51	46	46	39	55	42	42	44	48	48	48	48	48	48	52
57	4497.75	51	43	49	43	49	42	42	44	44	44	44	44	44	44	44
53	4498.00	43	49	49	43	43	47	53	50	51	51	51	51	51	51	52
58	4498.12	55	49	49	48	48	45	45	44	44	44	44	44	44	44	44
65	4498.12	52	48	47	47	47	53	53	50	51	51	51	51	51	51	52
54	4498.25	39	47	47	47	47	47	47	47	47	47	47	47	47	47	47
55	4498.37	35	43	43	43	43	43	43	43	43	43	43	43	43	43	43
56	4498.62	36	44	44	44	44	44	44	44	44	44	44	44	44	44	44
57	4498.75	47	53	53	46	46	46	46	46	46	46	46	46	46	46	46
66	4498.75	52	46	46	46	46	46	46	46	46	46	46	46	46	46	46
58	4499.12	32	41	41	41	41	41	41	41	41	41	41	41	41	41	41

TABLE I.- AVAILABLE LANDMARKS - Continued

Landmark no	Time of acquisition, t, min e.e.t.	θ, deg			at t plus 30 sec	at t plus 37.5 sec	at t plus 45 sec	at t plus 52.5 sec					
		at t plus 7.5 sec	at t plus 15 sec	at t plus 22.5 sec									
(a) Day 3 - Continued													
Second sighting pass - Concluded													
68	4499.37	54	49	42	35	28	25	27					
69	4499.50	53	48	43	37	33	33	36					
66	4499.87	43	49	55			36	41					
68	4500.37	40	47	53	28	22	28						
71	4500.37	50	44	36									
69	4500.50	47	52										
72	4500.50	55	49	41	32	21	8	21					
73	4501.00	51	44	35	25	12	2	28					
74	4501.25	54	49	43	37	32	30						
71	4501.37	44	50										
72	4501.50	32	41	48	54								
73	4502.00	38											
Third sighting pass													
8	4582.37	53	47	40	31	22	17	22					
9	4582.87	53	48	42	37	35	35	39					
10	4582.87	53	48	42	35	29	27	31					
11	4583.25	55	49	42	33	23	14	15					
8	4583.37	39	47	53									
9	4583.87	49	54										
10	4583.87	44	50										
11	4584.25	35	43	50									
15	4585.25	54	54										
16	4585.25	55	55										
22	4586.75	50	43	35	25	16	15	23					
23	4588.50	53	48	55	38	35	36	39					
24	4588.75	53	48	42	41	40	41	45					
23	4589.50	49	54										

TABLE I.- AVAILABLE LANDMARKS - Continued

Landmark no	Time of acquisition t, min g.e.t.	at t plus 7.5 sec	at t plus 15 sec	at t plus 22.5 sec	θ, deg at t plus 30 sec	θ, deg at t plus 37.5 sec	θ, deg at t plus 45 sec	θ, deg at t plus 52.5 sec
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(a) Day 3 - Concluded

Third sighting pass - Concluded								
25	4589.50	54	52	51	52	54	54	49
24	4589.75	53	52	42	40	40	45	
26	4589.75	54	47					
27	4591.00	51						
126	4592.00	54						
126	4593.00	54	48	41	34	26	22	30
125	4593.12	50	44	38	32	29	30	41
127	4593.87	54	53	52	52	54		
126	4594.00	38	45	51	38	36	37	46
128	4594.00	51	46	41				
125	4594.12	47	52					
128	4595.00	51						
70	4595.25	54	52	50	49	50	51	41
130	4595.25	54	52	50	49	50	52	
145	4604.25	55	50	43	36	27	17	
144	4604.87	55	53	53	52	54	54	14
145	4605.25	23	32	40	47	52		

Fourth sighting pass								
107	4687.87	55	50	46	41	38	36	41
108	4687.87	52	46	39	29	19	8	21
109	4688.12	54	50	47	44	42	43	48
106	4688.37	54	53	53	54			
107	4688.87	46	50	55	53			
108	4688.87	32	40	47				
109	4689.12	52						

TABLE I.- AVAILABLE LANDMARKS - Continued

Landmark no	Time of acquisition, t, min g.e.t.	θ, deg						at t plus 52.5 sec	at t plus 45 sec	at t plus 52.5 sec			
		at t plus 7.5 sec	at t plus 15 sec	at t plus 22.5 sec	at t plus 30 sec	at t plus 37.5 sec							
(b) Day 6													
		First sighting pass											
008	8572.12	41	29	15	3	18	32	43	51				
009	8572.00	52	48	44	43	44	48	53		52			
010	8572.62	49	41	30	18	12	22	34		46			
011	8573.00	50	43	36	32	44	33	39					
011	8574.00	52											
018	8575.50	53	53	54									
020	8576.75	55	52	50									
037	8578.75	53	47	42	39	41	46	52					
044	8579.62	48	38	25	8	11	27	40		50			
045	8579.62	51	44	35	29	29	36	45		52			
043	8579.75	54	49	42	38	38	42	48		54			
209	8593.62	51	45	41	40	43	49	54					
212	8596.75	53	51	51	53								
213	8596.75	50	46	43	42	45	50	54					
214	8596.75	54	48	40	32	28	30	37		45			
214	8597.75	52											
222	8604.87	51	46	40	36	35	38	42		47			
222	8605.87	52	49	47	45	46	48	51		54			
239	8609.37	52	47	42	39	37	38	41		45			
238	8611.00	51	49	54									
238	8612.00	49	54	48	41	33	23	13		18			
237	8611.12	54											
237	8612.12	28	37	44	50	42	40	42		45			
236	8611.50	54	50	46	38	29	19	5		17			
240	8613.50	51	45	38	50	55	55						
240	8614.50	28	37	44									

TABLE I.— AVAILABLE LANDMARKS — Continued

Landmark no	Time of acquisition t, min g.e.t.	at t plus 7.5 sec	at t plus 15 sec	at t plus 22.5 sec	θ, deg	at t plus 30 sec	at t plus 37.5 sec	at t plus 45 sec	at t plus 52.5 sec
006	8665.62	55	50	46	47	45	46	50	54
018	8667.87	53	46	42	37	36	40	47	47
018	8668.87	55	49	46	42	42	46	51	53
020	8670.62	51	46	46	36	24	17	25	37
037	8672.62	54	46	46	34	22	17	27	39
038	8673.25	54	46	44	43	45	49	54	47
038	8674.25	55	44	44	31	25	28	38	47
039	8677.25	53	45	45	34	22	15	25	37
046	8673.75	50	45	45	43	45	49	54	49
047	8673.75	49	40	40	31	25	28	38	47
049	8674.12	53	45	45	34	22	15	25	37
048	8674.25	52	50	50	50	52	51	55	52
052	8674.75	54	50	48	48	48	51	44	54
050	8674.87	48	41	34	34	32	37	47	47
051	8675.00	53	49	45	45	44	47	52	52
053	8675.37	55	52	51	51	52	55	55	55
225	8700.50	52	46	38	29	19	19	9	11

(b) Day 6 — Continued

Second sighting pass									
010	8760.50	49	40	31	25	28	38	47	54
011	8761.00	52	47	44	44	47	51	47	50
021	8764.12	53	52	52	54	43	42	45	50
024	8766.50	54	54	52	47	43	42	45	50
024	8767.50	55	41	28	12	7	24	38	48
059	8768.12	51	42	28	16	13	26	38	48
060	8768.75	51	42	30	15	8	23	37	47
061	8768.75	51	42	35	26	23	30	40	49
061	8769.75	55	45	37	31	30	35	43	51
062	8769.25	53	46						
129	8771.37	53							

Third sighting pass

Third sighting pass									
010	8760.50	49	40	31	25	28	38	47	54
011	8761.00	52	47	44	44	47	51	47	50
021	8764.12	53	52	52	54	43	42	45	50
024	8766.50	54	54	52	47	43	42	45	50
024	8767.50	55	41	28	12	7	24	38	48
059	8768.12	51	42	28	16	13	26	38	48
060	8768.75	51	42	30	15	8	23	37	47
061	8768.75	51	42	35	26	23	30	40	49
061	8769.75	55	45	37	31	30	35	43	51
062	8769.25	53	46						
129	8771.37	53							

TABLE I.- AVAILABLE LANDMARKS - Continued

Landmark no	Time of acquisition, t, min g.e.t.	at t plus 7.5 sec			at t plus 15 sec			at t plus 22.5 sec			θ, deg		
		at t plus 7.5 sec	at t plus 15 sec	at t plus 30 sec	at t plus 37.5 sec	at t plus 45 sec	at t plus 52.5 sec	at t plus 45 sec	at t plus 52.5 sec	at t plus 45 sec	at t plus 52.5 sec	at t plus 45 sec	at t plus 52.5 sec
(b) Day 6 - Continued													
131	8772.37	50	44	37	34	36	42	49	48				
132	8772.50	51	43	33	24	21	29	39	48				
132	8793.50	55	51	47	46	48	51	51	44				
134	8773.62	55	51	32	20	13	21	33	44				
135	8774.50	51	43	48	48	51	54	53	53				
136	8776.62	52	49	39	36	37	41	47	40				
137	8778.00	50	45	29	15	2	16	30					
138	8779.00	49	40	55	53	54	54						
138	8780.00	48	55	52	50	50	52						
139	8780.75	53	51	50	45	41	39						
141	8781.62	54	51	50	45	41	39						
142	8781.62	55	50	43	34	24	17						
143	8781.75	50	43	52	53	54	54						
143	8782.25	45	52	53	50	50	52						
144	8782.12	54	53	48	42	37	36						
030	8861.87	54	48	42	32	25	26						
031	8862.00	50	42	41	29	18	17						
028	8862.12	55	51	50	52	50	52						
029	8862.12	53	51	49	49	50	52						
032	8862.25	50	41	30	16	7	7						
033	8862.25	54	51	42	35	32	35						
034	8863.25	50	42	55	38	31	30						
034	8864.25	52	55	46	42	48	50						
035	8863.37	53	49	49	47	43	45						
103	8864.37	55	49	42	35	32	35						
103	8865.37	53	53	53	54	54	54						
101	8864.50	54	53	49	47	48	50						
102	8864.50	53	51	47	43	42	45						
105	8864.75	51	54	54	54	54	53						
104	8865.62	55											

Third sighting pass - Concluded

TABLE I.- AVAILABLE LANDMARKS - Concluded

Landmark no	Time of acquisition, $t$ , min g.e.t.	$\theta$ , deg					
		at $t$ plus 7.5 sec	at $t$ plus 15 sec	at $t$ plus 22.5 sec	at $t$ plus 30 sec	at $t$ plus 37.5 sec	at $t$ plus 45 sec

(b) Day 6 - Concluded

Fourth sighting pass

146	8875.75	55	50	44	38	32	29	30	35
146	8876.75	41	47	52					
147	8875.75	51	47	43	41	40	42	45	49

TABLE II.- NOMINAL LANDMARK SIGHTING SCHEDULE

Acquisition g.e.t.		Landmark		Location	View time, sec	Alternate landmarks in area.
Total min	Days:hr:min:sec	(a) Day 3				
First sighting pass						
4383.87	3:1:03:52.2	4 or unknown	Hawaii		30.0	
4393.75	3:1:13:45.0	10	Gulf of Calif.		60.0	
4400.75	3:1:20:45.0	45	N Florida		75.0	44, 46
4427.00	3:1:47:00.0	224	W Angola		82.5	
4432.00	3:1:52:00.0	Unknown if lighted	Africa			
Second sighting pass						
4476.50	3:2:36:30.0	Unknown	Fr. Frigate Schoals			
4487.25	3:2:47:15.0	6	San Diego, Calif.		75.0	5
4492.25	3:2:52:15.0	20	Galveston, Texas		82.5	21
4498.75	3:2:58:45.0	66	Dominican Rep.		75.0	51, 52, 56, 72
Third sighting pass						
4568.60	3:4:08:36.0	Unknown	Midway Islands		67.5	a <sub>8</sub> , a <sub>9</sub>
4582.87	3:4:22:52.2	10	Gulf of Calif.			
4586.75	3:4:26:45.0	22	Tampico, Mexico		75.0	23
4593.00	3:4:33:00.0	126	N Columbia		75.0	125, 127

<sup>a</sup>Difficult to perceive

TABLE II.- NOMINAL LANDMARK SIGHTING SCHEDULE - Continued

Acquisition g.e.t.		Landmark		View time, sec	Alternate landmarks in area		
Total min	Days:hr:min:sec		Location				
(a) Day 3 - Continued							
Third sighting pass							
4599.00	3:4:39:39.0	Unknown	Central Brazil	128			
4604.25	3:4:44:15.0	145	Salvador, Brazil	90.0			
Fourth sighting pass							
4688.12	3:6:08:52.2	109	W Ecuador	60.0	<sup>a</sup> 107		
	7.2		Unknowns till dark		<sup>a</sup> 108		
(b) Day 6							
First sighting pass							
8572.62	5:22:52:37.2	10	Gulf of Calif.	52.5	<sup>a</sup> 8, <sup>a</sup> 9		
8579.62	5:22:59:37.2	45	N Florida	52.5	<sup>a</sup> 4, 37		
8596.75	5:23:16:45.0	214	W Guinea	60.0	213		
8604.87	5:23:24:52.2	222	W Angola	60.0			
8609.37	5:23:29:22.2	239	Central Africa	52.5	<sup>a</sup> 238		
8613.37	5:23:33:22.2	240	S Madagascar	90.0			

<sup>a</sup>Difficult to perceive

TABLE II.- NOMINAL LANDMARK SIGHTING SCHEDULE - Continued

Acquisition g.e.t.		Landmark	Location	View time, sec	Alternate landmarks in area
Total min	Days:hr:min:sec				

## (b) Day 6 - Continued

Second sighting pass					
8665.62	6:0:25:37.2	6	San Diego, Calif.	45.0	
8670.62	6:0:30:37.2	20	Galveston, Texas	45.0	37, 38, 39
8675.37	6:0:34:58.2	<sup>a</sup> 53 or unknown	Bahama Islands	30.0	50, 51
8700.50	6:1:00:30.0	225	Southwest Africa	82.5	

## Third sighting pass

Third sighting pass					
8746.40	6:1:46:24.0	Unknown if lighted	Fr. Frigate Schoals	52.5	
8760.50	6:2:00:30.0	10	Gulf of Calif.	52.5	11
8766.50	6:2:06:30.0	<sup>a</sup> 24	Merida, Mexico	60.0	59, 60, 61, 62
8771.37	6:2:11:22.0	129	Island N of Venezuela	52.5	
8776.62	6:2:16:37.2	136	French Guiana	37.5	137, 138
8781.75	6:2:21:45.0	143	East Brazil	67.5	141, 142

<sup>a</sup>Difficult to perceive

TABLE II.- NOMINAL LANDMARK SIGHTING SCHEDULE - Concluded

Acquisition g.e.t.		Landmark	Location	View time, sec	Alternate landmarks in area
Total min	Days:hr:min:sec				

(b) Day 6 - Concluded

Fourth sighting pass

8802.00	6:3:42:00.0	31	W Costa Rica	52.5	32, 33
8867.00	6:3:47:00.0	Unknown	S America		
8871.00	6:3:51:00.0	Unknown	S America		
8876.00	6:3:56:00.0	147	E Brazil	60.0	13 $\frac{1}{4}$

TABLE III.- TIMES FOR GROUND UPLINK AND  
IMU ALIGNMENT

Ground station	Approximate g.e.t., <sup>a</sup> hr:min	Event
(a) Third day		
HTV	71:50	State vector update time tagged to 73 <sup>h</sup> 00 <sup>m</sup> . Landmark schedule uplinked
First sighting pass		
CRO, CNB	72:25	P52 IMU realign
Second sighting pass		
CRO	73:55	P52 IMU realign
CRO	74:10	State vector update (optional)
Third sighting pass		
CRO	75:25	P52 IMU realign
CRO, GWN	75:45	State vector update (optional)
(b) Sixth day		
TEX	139:45	State vector update
CRO	140:35	P51 IMU orientation
HTV	141:20	Landmark schedule uplinked
First sighting pass		
CRO	142:10	P52 IMU realign
Second sighting pass		
CRO	143:35	P52 IMU realign

<sup>a</sup>Approximate times from reference 5.

TABLE III.- TIMES FOR GROUND UPLINK AND  
IMU ALIGNMENT - Concluded

Ground station	Approximate g.e.t., <sup>a</sup> hr:min	Event
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(b) Sixth day - Concluded

Third sighting pass

CRO	145:10	P52 IMU realign
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TABLE IV.- WEIGHTING STRUCTURE LOAD<sup>a</sup>(a)  $3 \times 3$  Mode on the third day

WORPOS, ft . . . . .	0
WORBEVEL, ft/sec . . . . .	0
WLMK, ft	
Known landmark . . . . .	10 000
Unknown landmark; hardwired . . . . .	1 500

(b)  $9 \times 9$  Mode on the sixth day

WORPOS, ft . . . . .	200
WORBEVEL, ft/sec . . . . .	0.2
WLMK, ft	
Known landmark . . . . .	500
Unknown landmark; hardwired . . . . .	1 500

<sup>a</sup>WORPOS - initial value for vehicle position portion of W matrix

WORBEVEL - initial value for vehicle velocity portion of W matrix

WLMK - initial value for landmark position portion of W matrix

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